

Duality in Probabilistic Automata

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- Special case of this construction known since 1962 to Brzozowski.
- Works for probabilistic automata.
- Seems interesting for learning and planning.
- Could be connected to duality in control theory, Pontryagin duality or general concrete dualities.
- We are not sure about the “right” categorical setting.



Deterministic Automata

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- $\gamma : Q \rightarrow 2^P$ or $\gamma : Q \times P \rightarrow 2$ is a labeling function.
- If $P = \{\text{accept}\}$ we have ordinary deterministic finite automata.



A Simple Modal Logic

- Thinking of the elements of P as formulas we can use them to define a simple modal logic. We define a *formula* φ according to the following grammar:

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- Now we define $\llbracket \varphi \rrbracket_{\mathcal{A}} = \{s \in Q \mid s \models \varphi\}$.



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- Note that another way of defining this equivalence relations is

$$\varphi \sim_{\mathcal{A}} \varphi' := \forall s \in Q. s \models \varphi \iff s \models \varphi'.$$



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- Since there is more than just one proposition in general the relation \equiv is finer than the usual equivalence of automata theory.



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The intuition

We have interchanged the states and the observations or propositions; more precisely we have interchanged equivalence classes of formulas - based on the observations - with the states. We have made the states of the old machine the observations of the dual machine.



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- each \mathcal{A}' -state is an equivalence class of \mathcal{A} -formulas.
- Thus we can look at states in \mathcal{A}'' as collections of \mathcal{S} -formula equivalence classes.



The Double Dual 2

- Let \mathcal{A}'' be the double dual, and for any state $s \in Q$ in the original automaton we define

$$\text{Sat}(s) = \{ \llbracket \varphi \rrbracket_{\mathcal{A}} : s \models \varphi \}.$$



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- The proof is by an easy induction on φ .



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- If we define a notion of bisimulation we can show that a machine and its double dual are bisimilar.
- The minimality is, of course, due to the use of the equivalence relations in the duality.



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- The double dual is always deterministic.



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- This gives the minimal DFA recognizing the same language. The intermediate step can blow up the size of the automaton exponentially before minimizing it.



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- We could make things continuous but that is orthogonal.



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- In POMDPs we assume actions are always accepted but with each transition some propositions are true, or some boolean observables are “on.”
- Note that the observations can depend probabilistically on the action taken and the *final* state. Many variations are possible.



Formal Definition of a POMDP

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Automata with State-based Observations

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- A **probabilistic automaton with stochastic observations** is

$$\mathcal{F} = (S, \Sigma, \mathcal{O}, \delta : S \times \Sigma \times S \rightarrow [0, 1], \gamma : S \times \mathcal{O} \rightarrow [0, 1]).$$



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- The explicit definition of these functions are:

$$\llbracket o \rrbracket_{\mathcal{E}}(s) = \gamma(s, o)$$

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- In AI these are called “e-tests.”



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- An easy calculation shows:

$$\begin{aligned} & \llbracket a_1 a_2 \cdots a_k o \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) \\ &= \llbracket a_1 a_2 \cdots a_k o \rrbracket_{\mathcal{E}}(s). \end{aligned}$$



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$$\llbracket o_1 a_1 o_2 a_2 o_3 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) =$$

$$\llbracket o_1 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}''}) \cdot \llbracket a_1 o_2 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) \cdot \llbracket a_1 a_2 o_3 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) .$$

This does not hold in the primal.



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$$\llbracket o_1 a_1 o_2 a_2 o_3 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) =$$

$$\llbracket o_1 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}''}) \cdot \llbracket a_1 o_2 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) \cdot \llbracket a_1 a_2 o_3 \rrbracket_{\mathcal{E}''}(\llbracket s \rrbracket_{\mathcal{E}'}) .$$

This does not hold in the primal.

- The double dual does not conditionalize with respect to intermediate observations.



More General Tests

- Recall the definition of a POMDP

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Some Notation

- We need to generalize the transition function to keep track of the final state.

$$\delta_{\epsilon}(s, s') = \mathbf{1}_{s=s'} \quad \forall s, s' \in S$$

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- We have written $\mathbf{1}_{s=s'}$ for the indicator function.
- We define the symbol $\langle s|t|s' \rangle$ which gives the probability that the system starts in s , is subjected to the test t and ends up in the state s' ; similarly $\langle s|e|s' \rangle$.



Notation continued

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- the states of the primal machine become the observations of the dual machine.



The Dual Machine

- We define the dual as $\mathcal{M}' =$

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The Main Theorem

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- The main result is: The probability of a state s in the primal satisfying a experiment e , i.e. $\langle s|e\rangle$ is given by $\langle [s]_{\mathcal{M}'}|[e]_{\mathcal{M}}\rangle = \gamma''([s]_{\mathcal{M}'}|[e]_{\mathcal{M}})$, where $[s]$ indicates the equivalence class of the e-test on the dual which has s as an observation and an empty sequence of actions.



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- There should be no such thing as absolute state! State is just a summary of past observations that can be used to make predictions.
- The double dual shows that the state can be regarded as just the summary of the outcomes of experiments.



We have a paper in the upcoming AAAI conference showing how to use the double-dual to represent systems with hidden state.



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- A a set and $T : \text{Set} \rightarrow \text{Set}$ is the functor $TS = S \times A$.



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- S is the set of states, A the actions and P the propositions.



Morphisms of Machines

- A morphism m from

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$$\begin{array}{ccc} S_1 \times A & \xrightarrow{f \times id_A} & S_2 \times A \\ \delta_1 \downarrow & & \downarrow \delta_2 \\ S_1 & \xrightarrow{f} & S_2 \end{array} \quad \text{and} \quad \begin{array}{ccc} S_1 \times P_2 & \xrightarrow{f \times id_{P_2}} & S_2 \times P_2 \\ id_{S_1} \times g \downarrow & & \downarrow \gamma_2 \\ S_1 & \xrightarrow{\gamma_1} & S_2 \end{array}$$



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- The contravariant functor $'$ sends \mathcal{M} to \mathcal{M}' , the dual defined before, and the morphism $(f, g) : \mathcal{M}_1 \rightarrow \mathcal{M}_2$ to (g', f) where

$$g'(\llbracket (w, p) \rrbracket_{\mathcal{M}_2}) = \llbracket (w, g(p)) \rrbracket_{\mathcal{M}_1}.$$



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- We define the *reduction* functor to be ' composed with itself i.e. ''.
- if $\mathcal{M} = \mathcal{M}''$ we say that it is completely reduced.



The Disappointment

- It would be very pleasant if we took $Q : \text{Mch} \rightarrow \text{Mch}^{op}$ and $R : \text{Mch}^{op} \rightarrow \text{Mch}$ to be the two (covariant) functors that represent ' and get $Q \dashv R$.



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- a map $g : [\mathcal{F}_{\mathcal{M}}] \times P \rightarrow \mathbf{2}$.
- Unless \mathcal{M} is proposition reduced there is no reason at all for such a thing to exist.



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- We proved that this machine was state reduced.
- We quietly ignored the extra propositions in the double dual.



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- $[s]_{\mathcal{M}} := \{s' \in S \mid \forall \phi \in \mathcal{F}, s' \models \phi \iff s \models \phi\}$ and $\bar{\delta}([s]_{\mathcal{M}}, a) := [\delta(s, a)]_{\mathcal{M}}$ and $[s]_{\mathcal{M}}\bar{\gamma}p \iff s\gamma p$.



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- We are experimenting with these ideas for practical problems in the RL Lab at McGill; joint with Doina Precup and Joelle Pineau.
- Extension to continuous observation and continuous state spaces.
- It is possible to eliminate state completely in favour of histories; when can this representation be compressed and made tractable?

